

μCORS-10 / -10C μCORS-30 / -30C micro coriolis rate sensor

Northrop Grumman LITEF is a world leading company with 60 years of experience in Inertial Systems Technology. With its new generation MEMS (Micro Electro Mechanical Systems) technology sensors, LITEF continues to design high accuracy sensors to meet current and future requirements.

MEMS sensor design at LITEF started in the early nineties with the B-290, a full silicon accelerometer. This accelerometer has been qualified in systems for navigation, attitude heading reference, stabilization and guidance.

LITEF's extensive experience with its Fiber Optic Gyros and the MEMS Accelerometer Triad B-290, was the basis of the μ CORS (Micro Coriolis Rate Sensor) design, resulting in the following advantages for the user:

- High performance under high vibration and shock levels in an extended temperature range
- \cdot High bandwidth
- High dynamic range (closed loop sensor)
- High scale factor linearity
- Temperature compensated data output
- High reliability

- Small size, low weight, low power consumption
- Flexible, configurable digital interface with multiple range, resolution and measurement mode options
- Tools available for flexible interface
 configuration

APPLICATION BENEFITS

- Improves system performance
- · Operates in harsh environment
- Reduces integration and logistic complexity
- · Reduces weight, volume, power, costs
- · LITEF support during integration

TYPICAL APPLICATIONS

The μ CORS is designed to meet the requirements of the most demanding stabilization and pointing applications; including but not limited to

- Platform stabilization for land, sea, and aerial systems e.g. camera stabilization for aerial survey
- Navigation, guidance, stabilization and control systems for unmanned and manned applications



TECHNICAL DATA

MICRO CORIOLIS RATE SENSOR

PERFORMANCE														
		µCORS-10	µCORS-10C	µCORS-30	µCORS-30C									
Measurement Range	°/s	± 1000	± 499	± 1000	± 499									
Rate Bias (1 σ), full temperature	°/h	≤1	≤1	≤3	≤3									
Scale Factor Error - Day-to-Day (1 σ), full temperature	ppm	<	500	≤ 1000										
Angular Random Walk ¹⁾	°/ √h	≤	0.05	≤ 0.08										
Vibration Rectification Error (RMS)	°/h/g²	≤ 0.3												
Start-up Time (full performance)	S	≤1												
Axis Misalignment Repeatability	mrad (max)	± 10												
Axis Misalignment Stability	mrad (max)	±1												
Bandwidth (-3 dB) ¹⁾	Hz	≥ 300												
ELECTRICAL CHARACTERISTICS														
Supply Voltage	VDC	+5												
Power Consumption	W	< 2.2												
Connector		D-Sub Micro, 15 pins, female												
Digital Serial Data Interface - asynchronous (RS-422) - synchronous	Bd	9600 375,000												
(IBIS, based on CCITT 1431T1/E19)	MHz	up to 2.048												
Configurability asynchronous interface only:		Data Size & Resolution, Mode (Angular Increments, Rate, Accumulated Angle) Baudrate, Trigger Mode (HW, SW, Autonomous), Update Rate												
PHYSICAL CHARACTERISTICS														
Dimensions	mm	51 x 51 x 23 (w/o connector)												
Weight	g	≤ 85												
ENVIRONMENTAL CONDITIONS														
Temperature Range (operational)	°C	-40 to +65												
Vibration (operational)	g _{RMS}	10.88 (10 Hz to 2 kHz)												
Shock (operational)	g/ms	100 / 11, 250 / 4, 500 / 2												

¹⁾ Other noise/bandwidth ratio: on request

FOR MORE INFORMATION,	L	L.	L	L.	L	L	L.	L.	L.	L	L.	L.	L	L	L.	L	L.	L.	L	L.	L	L	L	L	L.	L	L.	L.	L
PLEASE CONTACT:	L.	E.	L.																										
Northrop Grumman LITEF GmbH	L	L.	L.	L.	L	L.	L.	L.	L.	L	L.	L	L.	L	L.	L	L	L.	L										
Lörracher Strasse 18	L	L.	L	L.	L.	L.	L.	L.	L	L.	L.	L.	L.	L	L.	L													
79115 Freiburg Germany	L	L.	L	Ľ,	L.	Ľ,	L.																						
Phone: +49 761 4901-0	L.	E.	L.																										
info@litef.de www.litef.com	L	L,	L,	L,	L	L	L.	L.	L.	L	L.	L.	L.	L	L.	L.	L.	L.	L	L.	L.	L.	L.	L	L,	L.	L,	L,	L